## Problem Tutorial: "Add One"

Note that for $x=(? ? ? ? 0 \underbrace{11 \cdots 11}_{k})_{2}, x+1$ equals to $x \oplus\left(2^{k+1}-1\right)$. So we can enumerate the value of $k$, and check if we can get a value in the form of $(? ? ? ? 0 \underbrace{11 \cdots 11}_{k})_{2}$. This can be done by using the linear basis.

Time Complexity is $O\left(n w^{2}\right)$ if we assume $a_{i}=O\left(2^{w}\right)$. It can also be optimized to $O((n+w) \cdot w)$ (but is not required).

## Problem Tutorial: "Be Careful"

Let's denote the set of the sons of vertex $u$ as $S_{u}$, and $d_{u}=\left|S_{u}\right|, \delta_{u}=\max _{v \in S_{u}} d_{v}, t_{u}=\sum_{v \in S_{u}}\left[d_{v}>0\right]$. Note that for all non-leaf vertex $u$, the number written on vertex $u$ will be between 0 and $d_{u}$.

Our first insight is using dynamic programming to solve the problem. Let $f_{u, v}$ denotes the number of ways to fill the subtree of the vertex $u$, so that the number writing on vertex $u$ will be exactly $v$.

## Part 1

The first way to calculate $f$ is using the inclusion-exclusion principle. Let $d p_{S}$ be the number of ways if all the numbers written on its children don't belong to $S$. First, it seems we need $O\left(2^{d_{u}}\right)$ states, but note that we don't need to add the contribution of the leaf children to the state. So there are only $O\left(2^{\delta_{u}}\right)$ states.

## Part 2

The second way to calculate $f$ is using bitmasks dp. Let $f_{i, S}$ be the number of ways that:

- Let's fill the numbers from small to large,
- We have considered the numbers $0,1, \cdots, i$,
- The set of unfilled sons is $S$

There will be $O\left(d_{u} \cdot 2^{d_{u}}\right)$ states. But we can also treat all leaves independently. Let's add a dimension $[k]$ in our dp, which means an additional constraint that there are $k$ leaves that have been filled. By using SOS dp, the time complexity will be $O\left(2^{t_{u}} \cdot \operatorname{poly}\left(t_{u}\right)\right)$

## Part 3

If we use these two ways at the same time, we will have an $O\left(\min \left(2^{t_{u}} \cdot \operatorname{poly}\left(t_{u}\right), 2^{\delta_{u}} \cdot \operatorname{poly}\left(\delta_{u}\right)\right)\right)$ solution, but it's still not enough to pass it, because $t_{u}$ and $\delta_{u}$ can be large at the same time.

So let's try to split the set of the sons of $u$ and use an sqrt-decomposition-like process. For a threshold $B$, let's split all the sons with $d_{v} \leq B$ to the set $A_{u}$, and the others to the set $B_{u}$.
Let's run the DP described in Part 1 for $A_{u}$, and run the DP described in Part 2 for $B_{u}$ simultaneously. When solving $A_{u}$, we need to know the states in $B_{u}$. Let $l=\left|B_{u}\right|$, then the time complexity will be $O\left(2^{B+l}\right)$.
Note that if all $B+l$ is at least $M$, then we have $\sum_{v} d_{v} \geq \frac{M(M+1)}{2}$, but $\sum_{i} d_{i}=n-1$, so $M=O(\sqrt{n})$ (or more precisely, $M \sim \sqrt{2 n}$ ).
By selecting an optimal $M$ while doing the dp process, the time complexity will be $O\left(2^{\sqrt{2 n}} \cdot \operatorname{poly}(n)\right)$

## Problem Tutorial: "Counting Sequence"

Let $f_{i, j}$ be the sum of sequences that satisfy the sum of its elements is $i$ and the last element is $j$. We have $f_{0,0}=1, f_{i, 0}=0(i>0)$ and $f_{i, j}=c \cdot f_{i-j, j-1}+f_{i-j, j+1}$. But there are $O\left(n^{2}\right)$ reachable states, so it's not acceptable.

Note that if $a_{1}=B$, then the sum of $a_{1}, a_{2}, \cdots, a_{m}$ is not less than $\sum_{i=1}^{m}(B-i)=m B-\frac{m(m+1)}{2}$. Because the sum should be exactly $n$, the length of the sequence will be no more than $O(n / B)$.
So we can consider the sqrt-decomposition trick. If $a_{1} \leq B$, then we can run the naive DP solution, the time complexity is $O(n B)$. If $a_{1}>B$, then the length of the sequence is $O(n / B)$, and the maximum value of $\left|a_{i}-a_{1}\right|$ will also be $O(n / B)$. Let $g_{i, j, k}$ be the sum of sequences that satisfy:

- The length of the sequence is $i$
- $\sum_{t \leq i}\left(a_{t}-a_{1}\right)=j$
- $a_{i}-a_{1}=k$

The time complexity will be $O\left(n B+(n / B)^{4}\right)$. If we take $B=O\left(n^{3 / 5}\right)$, then the overall time complexity is $O\left(n^{8 / 5}\right)$. With some constant optimization, you might be able to pass it with this solution.
But we can actually go further. Let's not insert an element at the end of the sequence, but at the beginning of the sequence. Let $f_{i, j}$ be the sum of the sequences that satisfy the length of it is $i$, and the sum of $a_{t}-a_{1}=j$. When doing the transaction, we can either add an $a_{1}-1$ or $a_{1}+1$ as a new $a_{1}^{\prime}$, but note that it contributes $\sum\left(a_{t}-a_{1}\right)$ either $i$ or $-i$. The time complexity is $O\left(n B+(n / B)^{2}\right)$, which is $O(n \sqrt{n})$ if we take $B=O(\sqrt{n})$.
After calculating $f_{i, j}$, we can just enumerate the value of $a_{1}>B$ and use the DP table to update the answer. The time complexity is $O(n \sqrt{n})$ ).

## Problem Tutorial: "DS Team Selection"

For each modification, let's consider its effect on the whole plane. For $d=3$, its modification matrix is:

| 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 0 | 1 | 1 | 1 | 1 | 1 | 0 |
| 0 | 1 | 2 | 2 | 2 | 1 | 0 |
| 0 | 1 | 2 | 3 | 2 | 1 | 0 |
| 0 | 1 | 2 | 2 | 2 | 1 | 0 |
| 0 | 1 | 1 | 1 | 1 | 1 | 0 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Taking its 2D difference, we can show that it is a matrix whose main diagonal consists of 1 and secondary diagonal consists of -1 .

| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 1 | 0 | 0 | 0 | 0 | -1 | 0 |
| 0 | 0 | 1 | 0 | 0 | -1 | 0 | 0 |
| 0 | 0 | 0 | 1 | -1 | 0 | 0 | 0 |
| 0 | 0 | 0 | -1 | 1 | 0 | 0 | 0 |
| 0 | 0 | -1 | 0 | 0 | 1 | 0 | 0 |
| 0 | -1 | 0 | 0 | 0 | 0 | 1 | 0 |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Let's try to maintain the 2D difference matrix. The modification of the diagonals of the matrix can be differentiated again into the modification of the two rays as follows. For each query $\mathrm{x} 1 \mathrm{y} 1 \times 2 \mathrm{y} 2$, the contribution on the difference matrix is of the form $\sum_{i=x_{1}}^{x_{2}} \sum_{j=y_{1}}^{y_{2}} \delta(i, j)\left(x_{2}-i+1\right)\left(y_{2}-j+1\right)$, so wee need to maintain:

- $\sigma=\sum \delta(i, j)$
- $\sigma_{x}=\sum i \delta(i, j)$
- $\sigma_{y}=\sum j \delta(i, j)$
- $\sigma_{x y}=\sum i j \delta(i, j)$


We now need to solve the problem of maintaining a two-dimensional plane that supports:

- (Modification 1): For all points $(x, y)$ that satisfy $x-y=d$ and $x \leq c$, increase its weight by $w$.
- (Modification 2): For all points $(x, y)$ that satisfy $x+y=d$ and $x \leq c$, increase its weight by $w$.
- (Query): For all points $(x, y)$ that satisfy $x \leq x_{0}$ and $y \leq y_{0}$, find the value of $\sigma, \sigma_{x}, \sigma_{y}$ and $\sigma_{x y}$.

Let's focus on the first type of modification. WLOG, let's assume that $x_{Q}-y_{Q} \leq x_{M}-y_{M}$, so the modification ray will pass through the side of the rectangle that is parallel to the $y$-axis (or more precisely, the line $\left.x=x_{Q}\right)$. Then, the contribution of the modification $\left(x_{M}, y_{M}, w\right)$ to the query $\left(x_{Q}, y_{Q}\right)$ is:


Modification 1

- $\Delta(\sigma)=\left(x_{Q}-x_{M}+1\right) \cdot w$
- $\Delta\left(\sigma_{x}\right)=\sum_{i=x_{M}}^{x_{Q}} i \cdot w=w \cdot \frac{\left(x_{Q}+x_{M}\right)\left(x_{Q}-x_{M}+1\right)}{2}$
- $\Delta\left(\sigma_{y}\right)=\sum_{i=x_{M}}^{x_{Q}}\left(i-x_{M}+y_{M}\right) \cdot w=\left(x_{Q}-x_{M}+1\right) \cdot\left(y_{M}-x_{M}\right) \cdot w+\frac{\left(x_{Q}+x_{M}\right)\left(x_{Q}-x_{M}+1\right)}{2} \cdot w$
- $\Delta\left(\sigma_{x y}\right)=\sum_{i=x_{M}}^{x_{Q}} i \cdot\left(i-x_{M}+y_{M}\right) \cdot w=\frac{x_{Q}\left(x_{Q}+1\right)\left(2 x_{Q}+1\right)-\left(x_{M}-1\right) x_{M}\left(2 x_{M}-1\right)}{6} \cdot w+\frac{\left(y_{M}-x_{M}\right)\left(x_{Q}+x_{M}\right)\left(x_{Q}-x_{M}+1\right)}{2} \cdot w$

Overall, the things we need to maintain are:

1. 0 -term: $\sum w$
2. 1-term: $\sum w \cdot x$ and $\sum w \cdot y$
3. 2-term: $\sum w \cdot x^{2}, \sum w \cdot x \cdot y$ and $\sum w \cdot y^{2}$
4. 3-term: $\sum w \cdot x^{3}, \sum w \cdot x^{2} \cdot y, \sum w \cdot x \cdot y^{2}$ and $\sum w \cdot y^{3}$

So we can use D\&C and Segment Trees (or Fenwick Tree) to solve this case.
For the second case, we can handle it manually or just rotate the plane and change it to the first case. The time complexity is $O\left(n \log ^{2} n\right)$ with a huge constant. Note that by using unsigned int overflow, we can get the answer modulo $2^{32}$, and we can divide everything by 6 after our calculation.

## Problem Tutorial: "Exciting Travel"

The problem is (almost) equivalent to assigning each vertex to at most one path. Your task is to maximize the number of paths such that all vertices in it have been assigned to it. Note that for two adjacent paths, the common endpoints of the two paths can be used twice.

For each query, let's build a virtual tree of the endpoints of the paths. Let $f_{u}$ denote the answer to the subtree of $u$. For $l_{i}=\operatorname{LCA}\left(p_{i}, p_{i+1}\right)$, enumerate whether this path is selected at $l c a$. Consider all transitions like $\sum_{u \in \operatorname{path}\left(p_{i}, p_{i+1}\right), v \notin \operatorname{path}\left(p_{i}, p_{i+1}\right)} f_{v}+1$.
Let $g_{u}=\sum_{v \in \operatorname{son}(u)} f_{v}-f_{u}$, this formula can be rewritten as $\sum_{u \in \operatorname{path}\left(p_{i}, p_{i+1}\right), u \neq l_{i}} g_{u}+1+f_{x}+f_{y}$, where $f a_{x}=f a_{y}=l_{i}, x \in \operatorname{path}\left(l_{i}, p_{i}\right), y \in \operatorname{path}\left(l_{i}, p_{i+1}\right)$. There is a slight difference when $p_{i}$ or $p_{i+1}$ is an ancestor of another. It is enough to maintain the prefix sum of $g$ in the process of dp. By using the small-to-large technique, the time complexity is $O(N \log N)$, where $N=n+\sum_{i=1}^{q} k_{i}$.

## Problem Tutorial: "Flower's Land"

## Solution 1

Consider centroid decomposition, the centroid is $r$, calculate the maximum value of the connected component of size $k$ that must contain $r t, u$. Notice that the path of $r t$ to $u$ must be selected, the remaining part can be divided into two parts: vertex with order greater than $d f n_{u}$ in preorder traversal and vertex with order less than or equal to $d f n_{u}-\operatorname{size}_{u}$ in the postorder traversal.
Let $f_{i, j}$ denote that the preorder traversal is $[i, n]$, where $j$ is selected and the order of $u, f a_{u}$ is $[i, n]$ and $u$ is selected, enumerate whether to select $u$ to decide whether to skip the subtree of $u$, then $f_{i, j}=\max \left(f_{i+1, j-1}+a_{u}, f_{i+s i z e}, j\right)$. Similarly, let $g_{i, j}$ denote the values of choice $j$ in the postorder traversal of $[1, i]$, which can be transferred similarly. To find the answer, you can $O(k)$ to combine the $k-\operatorname{dis}(r t, u)$ item of the two arrays. Terminate immediately when the size of the current connected component is less than k , so the time complexity is $O\left(n k \log \frac{n}{k}\right)$, which is enough to pass.

## Solution 2

Consider up and down dp, let $f_{u, i}$ denote the maximum value of the connected component of size $i$ in the subtree of $u$, and $g_{u, i}$ denote the maximum value of the connected component of size $i$ outside the subtree of $u$. Consider transition of $f, f_{u, x}=\max _{\sum_{v} s_{v}=x-1} f_{v, s_{v}}+a_{u}$. For the sons of $u v_{1}, v_{2}, \cdots, v_{m}$, in order to transition $g_{v_{i}}$, we define two auxiliary arrays $h_{i, j}^{(1)}$ denotes that outside the subtree $u$ and in the subtree of $v_{j}(j<i)$, a connected component of size $k-j$ can be selected. And, similarly, $h_{i, j}^{(2)}$ denotes that $j$ is selected from the subtree of $v_{j}(j>i)$ The maximum value of the vertex. Then there is $g_{v_{i}, j}=\max _{x-y=j} h_{i, x}^{(1)}+h_{i, y}^{(2)}$. Calculate $h^{(1)}, h^{(2)}$ can be done in a similar way to calculate $f$, with a time complexity of $O(n k)$.

## Problem Tutorial: "Games"

First, consider that no label is given, we can solve it with a tree dp. Let $f(u, i, 0 / 1)$ denote the number of ways in which only vertices inside the subtree $u$ is considered, $a_{u}$ is equal to $i$, and the subtree has/hasn't the value greater than $u$.
The transition is simple, with prefix sum optimization, and the time complexity is $O(n m)$.
Since only one label will be given, we can consider up and down dp. Similarly, let $g(u, i, 0 / 1)$ denote the number of ways in which only points outside the subtree $u$ is considered, $a_{u}$ is equal to $i$, and the subtree has/hasn't the value greater than $u$.
The transition from father $u$ to some son $v$ needs to use the $f$ values of u's sons other than $v$, this can be done by processing prefix/suffix sums.
Finally, the answer to the query can be calculated by combining $f_{u}$ and $g_{u}$.
The total time complexity $O(n m+q)$.

## Problem Tutorial: "Half Plane"

The intended solution is applying the algorithms described in Offline Optimal Range Query and Update Algorithm by Xinlong Li and Chengze Cai (also the author of this problem). The detailed explanation can be found here: https://qoj.ac/files/ISAAC_2021_paper_100.pdf
The key idea is to design a divide and conquer algorithm which works on the operation sequence. Let's separate the operation sequence into blocks of size $O(B)$. For each block of operations, we maintain a dynamic rooted forest, where each leaf node corresponds to a point. Notice that $B$ half-planes divide the plane into $O\left(B^{2}\right)$ regions. Two leaf nodes belong to the same rooted tree in the forest if and only if the corresponding points are currently in the same region on the plane.
When we recursively enter the side of the $\mathrm{D} \& \mathrm{C}$, some regions are merged and we merge the roots of the corresponding rooted trees. This is done by creating a new node $z$ and specifying the father of the roots of these trees as $z$. When we reach the corner case $l=r$, there exist only 2 regions, where one of them should be performed our modification or query. The whole process can be finished using a procedure similar to the Lazy Propagation.


The thing we left is to divide these points into regions effectively. You can refer to the methods of planar point location: Neil Sarnak and Robert Endre Tarjan. Planar point location using persistent search trees, https://doi.org/10.1145/6138.6151.
The time complexity is $\tilde{O}(n+m \sqrt{n})$, where $B=\tilde{O}(\sqrt{n})$. You can find a sample implementation here: https://qoj.ac/submission/36891

## Problem Tutorial: "Inverse Line Graph"

Consider that the problem is transformed into, assigning two colors to each vertex of the new graph, which represents the endpoints of the original graph, so it is necessary to ensure that the derived subgraph of any color is a complete graph, and each edge is in exactly one complete graph, An edge covered by the color is said to be in the derived subgraph of that color. We choose any vertex $u$ and consider dividing the outgoing edges of $u$ into two sets, representing two colors respectively. Let the out-degree of $u$ be $S$, and the sets of two colors are $S_{1}, S_{2}$ respectively. Assuming we get the partition right, for each vertex in $S$, the color has been used, and the remaining edges that are not covered, must become a new complete graph, so it can be processed recursively. Let $x \in S_{1}, y_{1}, y_{2} \in S_{2}$ and $\left(x, y_{1}\right),\left(x, y_{2}\right)$, then $\left(x, y_{1}\right)$ and $\left(x, y_{2}\right)$ must be covered a color, but The edges of $y_{1}$ to $y_{2}$ have been covered, so there is no solution. So the edges between $S_{1}, S_{2}$ are a match. Choose any $p \in S$, let $S_{1}=\{p\}, S_{2}=S-S_{1}$, and check it. Otherwise, Then there must be $p, q \in S_{1},(p, q)$. Suppose we have the initial condition of $p, q \in S_{1}$, then for $x \in S$, if there is an edge with $p, q$, it must be in $S_{1}$, otherwise in $S_{2}$. For $t \in S_{2},(p, t)$, check it again by the above method. If it is still not satisfied, it means that $p, q$ is not in a set, $p, t$ is not in a set, because $t \in S_{2}$, so $t, q$ has no edge so $t, q$ is not in a set, so there is no solution. Therefore, it can be converted into up to 3 times of testing, each time complexity $O(n+m)$. Total time complexity is $O\left(\sum n+\sum m\right)$.

## Problem Tutorial: "Just Another Number Theory Problem"

Consider that each number $x$ corresponds to a $n$ tuple ( $q_{x, 1}, q_{x, 2}, \cdots, q_{x, n}$ ), $q_{x, i}=x \bmod p_{i}$, which forms a set of bijective relations.
Note that $\left(a_{i}-a_{i-1}\right)^{2}$ equals to the number of ways to choose two numbers from $\left[a_{i-1}, a_{i}\right)$. Let's call these two numbers $l$ and $r$, and WLOG let $l \leq r$. Then for all $x$ in $[l, r]$, we have $x \bmod p_{i} \neq 0$ for all $1 \leq i \leq n$. That is, $q_{x, i}+r-l<p_{i}$. Let's enumerate $k=r-l$. For $0 \leq q_{x, i}<p_{i}-k$ there are $p_{i}-k$ values. Swap is also valid when $l \neq r$, so the answer is $\sum_{i=0}^{p_{1}-1}(1+[i>0]) \prod_{j=1}^{n}\left(p_{j}-i\right)$.
The time complexity is $O\left(n p_{1}\right)$.

## Problem Tutorial: "Kitten's Computer"

## Part 1: Design an Adder

We want to design an adder with rounding.
Define depth as the time required for the operation.
Half adder: $(a, b) \rightarrow(a \oplus b, a b)$ depth of 2 . Add the progression? Full adder $(a, b, c) \rightarrow(a \oplus b \oplus c, a b \oplus b c \oplus c a)$ with a depth of 3 . Doing so is not parallel and needs to be accelerated.
Carry-lookahead adder: additive rounds are always generated by $G=a b$ and then propagated through a series of $P=a \oplus b$.
Write the progression as $\bigvee_{j<i} G_{j} \prod_{j<k<i} P_{k}$, now need to parallelize it. Using multiplication, for $i=0,1, \cdots, 5$ Execute $G_{j} \leftarrow G_{j} \vee\left(P_{j} G_{j-2^{i}}\right), P_{j} \leftarrow P_{j} P_{j-2^{i}}$.
All $j$ is computed in parallel and the displacements can be pre-processed in advance. The depth is only 14.

Part 2: Design a Multiplier
Use the idea of vertical multiplication.

Use bitwise operations to separate each bit of a factor and then multiply it to get the mask. This gives us 64 numbers, now find a way to add them up.

Direct addition and partitioning will bring the depth of this step to 84, and the total depth of the version I wrote is 108 , so the adder will have to be optimized again.

Notice that the full adder converts the addition of 3 numbers into the addition of 2 numbers at a depth of 4 . Using this compression scale, $64 \rightarrow 44 \rightarrow 30 \rightarrow 20 \rightarrow 14 \rightarrow 10 \rightarrow 7 \rightarrow 5 \rightarrow 4 \rightarrow 3 \rightarrow 2$.
The depth can be compressed to 63 .

## Bonus

The depth can be further decreased to 59 .

## Problem Tutorial: "Long: WCWBTT"

The tutorial for the task will be added later. You can find the Chinese tutorial in advance before we finish the English one: https://qoj.ac/files/WCWBTT.pdf.
And more details about Weight Balanced Top Tree can be found here: https://zx2003.blog.uoj.ac/blog/7884.
You may check the sample implementation here: https://qoj.ac/submission/40652.

## Problem Tutorial: "Matrix Counting"

Let the continuous segment denote an interval in which both the range and position are continuous.
The problem we need to solve is to count the number of permutations that do not have consecutive segments of length $k+1, \ldots, n-1$. That is, the length of all consecutive segments, except the permutation itself, does not exceed $k$.

Assuming that we can replace all the current non-trivial consecutive segments (consecutive segments whose length is not 1 or $n$ ) with a number each time, then repeat the operation, and finally get a permutation without non-trivial consecutive segments. For the count of answers, we only care if the first replaced consecutive segment does not exceed $k$.

Suppose we count the number of permutations $F(x)$ (also called single permutations) without nontrivial consecutive segments, the answer seems to be $(F-x) \circ\left(\sum_{i=1}^{k} i!x^{i}\right)$.
However, this is incorrect. If the final permutation is $[1,2]$ or $[2,1]$, then we are not unique in how we replace consecutive segments. It depends on how many consecutive segments the current permutation can be divided into in just order or reverse order. So if this situation is not considered, the answer should be $\left(F-x-2 x^{2}\right) \circ\left(\sum_{i=1}^{k} i!x^{i}\right)$.
Let $P(x)=\sum_{i \geq 1} i!x^{i}$. Let's first consider the permutations that end up with [1, 2]. Consider the OGF $G(x)$ corresponding to each segment it is divided into. We have

$$
P=\sum_{i \geq 1} G^{i}=\frac{G}{1-G}
$$

$G(x)$ cannot get the number of permutations of $[1,2]$, and the permutations in $P(x)-G(x)$ can be divided by $G(x)$. That is

$$
G=\frac{P}{1+P}
$$

We consider how to get the permutation of $[1,2],[2,1]$ to satisfy the condition. Note that after division, any segment within an interval can constitute a continuous segment. Then we need to satisfy that the largest proper prefix and proper suffix do not exceed $k$. That is, the first and last paragraphs are not less than $n-k$. This part is

$$
\left[x^{n}\right] 2(P+1)\left(\sum_{i \geq n-k} g_{i} x^{i}\right)^{2}
$$

Next, we consider how to calculate a coefficient of $F$ and its composite $\sum_{i=1}^{k} i!x^{i}$. We split all permutations into two: permutations that would get $[1,2],[2,1]$ or not.
The formula for the terms that would get $[1,2],[2,1]$, which we have considered, is

$$
2(P-G)=2\left(P-\frac{P}{1+P}\right)=\frac{2 P^{2}}{1+P}
$$

and what will not get, is

$$
\left(F-x-2 x^{2}\right) \circ P=F(P)-P-2 P^{2}
$$

Then add the special case of length 1 to get

$$
\begin{gathered}
F(P)-P-2 P^{2}=P-\frac{2 P^{2}}{1+P}-x \\
\left(F-x-2 x^{2}\right) \circ H=H-\frac{2 H^{2}}{1+H}-P^{\langle-1\rangle}(H)
\end{gathered}
$$

Substituting $H(x)=\sum_{i=1}^{k} i!x^{i}$, we can solve this problem.
The key is to calculate $P^{\langle-1\rangle}(H)$. Let $A=P^{\langle-1\rangle}$, we first need to calculate $A$. By integer recurrence of $P$, the ordinary differential equation is

$$
P=x\left(1+P+x P^{\prime}\right)
$$

Substitute $x=A$, there is

$$
\begin{gathered}
x=A\left(1+x+A P^{\prime}(A)\right)=A\left(1+x+\frac{A}{A^{\prime}}\right) \\
x A^{\prime}=(1+x) A A^{\prime}+A^{2}
\end{gathered}
$$

Let $B=A(H)$, we have

$$
\frac{H}{H^{\prime}} B^{\prime}=\frac{1+H}{H^{\prime}} B B^{\prime}+B^{2}
$$

Let $C=H / H^{\prime}, D=(1+H) / H^{\prime}, E=B(D-1)$, we have

$$
\begin{cases}e_{n} & =\sum_{k=0}^{n-1} b_{k} d_{n-k} \\ -\left(b_{n}+e_{n}\right) & =\sum_{k=0}^{n-2}(k+1) b_{k+1}\left([k \neq 0]\left(e_{n-k}+b_{n-k}\right)-c_{n-k}\right)+\sum_{k=1}^{n-1} b_{k} b_{n-k}\end{cases}
$$

We can calculate everything by using D\&C and FFT in $O\left(n \log ^{2} n\right)$, which is able to pass.
The author's solution is using $O\left(n \log ^{2} n / \log \log n\right)$ approach for relaxed multiplication. You may find more details here:

- https://hly1204.blog.uoj.ac/blog/7319
- http://www.texmacs.org/joris/newrelax/newrelax.html


## Problem Tutorial: "No!"

We only care about the position where $h$ is the maximum value of the prefix, so after sorting the walls from largest to smallest, let $f_{i}$ denote that the $i$ wall must be selected, regardless of the answer that the $i$ will fall. Then there is $f_{i}=\max _{j=1}^{i-1} \min \left(f_{j}, \frac{h_{j}-h_{i}}{a_{j}}\right)$. For the contributions of two $j_{1}<j_{2}$, there is at most one intersection point regardless of the upper limit. So we can find a division point $p$, when $h_{i} \leq p$, then the decision point $j_{1}$ is not bad, when $f_{i}>p$ decision point $j_{2}$ is not bad. And we can find it in $O(1)$, so consider maintaining it in a method similar to CHT.
It can be done $O((n+q)(\log n+\log m))$, which is able to pass. If you use radix sort and gcd tricks, it can be done in $O(n+m+q), m=\max _{i=1}^{n} h_{i}$, but it is not required.

